Synthesis of Provably-correct Software using Discrete Control Theory

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Software @ Scale, Berkeley (08/18/2010)

Team

- University of Michigan
 - Students: Hongwei Liao, Hyoun Kyu Cho, Jason Stanley,
 - Faculty: Stephane Lafortune, Scott Mahlke
- HP Labs
 - Yin Wang, Terence Kelly
- Georgia Tech (recently)
 - Student: Ahmed Nazeem
 - Faculty: Spyros Reveliotis

Software Failures Are Costly

 Software bugs cost the U.S. economy an estimated \$59.5 billion annually

[National Institute of Standards and Technology, 2002]

- Post-release bugs are the worst
 - 100X increase in cost of removing defects
 [Barry Boehm, 1981]
 - on average, 11-25+ critical bugs are found within 12 months of the release, which cost \$5.2—22 million per company annually

[IDC white paper, 2008]

Multicore era brings new challenges

The Multicore Challenge

The Free Lunch Is Over A Fundamental Turn Toward Concurrency in Software

By Herb Sutter

The biggest sea change in software development since the OO revolution is

Patterson: Multicore is a Hail Mary pass



David Patterson writes in this month's IEEE Spectru multicore; a move that he characterizes as a Hail M yet know will be caught



April 19, 2008

Multicore Parallel Programming: Can We Please do it Right This Time? - IEEE Electronic Design Processes Workshop 2008

Steve Leibson

Tim Mattson, a principal engineer at Intel's Applications Research Laboratory, describe

With An 80-Core Chip On The Way, Software Needs To Start Changing

The big question is how -- and how soon -- the software industry will step up and produce applic that can take advantage of all those cores.

Cambrian Explosion of Research

New libraries, languages, features

Intel TBB, Erlang, Cilk++, atomic sections,
 Trans. Memory, OpenMP

Tools

- Static analysis, testing tools
 - Coverity[™], Locksmith
 - Klee, CHESS, CheckFence
- Runtime analysis
 - Eraser, Intel Thread Checker™
- Post-mortem analysis
 - Triage, CrashRpt

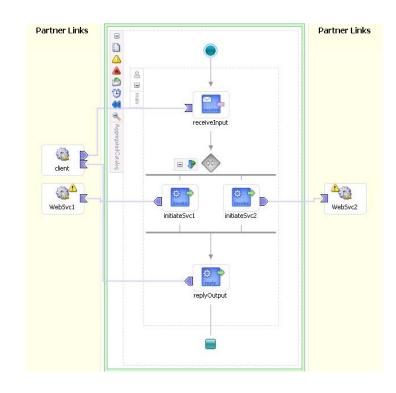


A New Angle---Control

- Goal: Controlling software execution to avoid failure
- Approach: Offline control synthesis + code instrumentation
- Foundation: Discrete Control Theory
- Paradigm: Control Engineering
- Application scenarios:
 - Rapid prototype development
 - Post-release bugs

Two Examples

- Workflow control [EuroSys 07]
 - High-level scripting language
 - Safe execution of flawed workflows
 - Ongoing effort at HP Labs

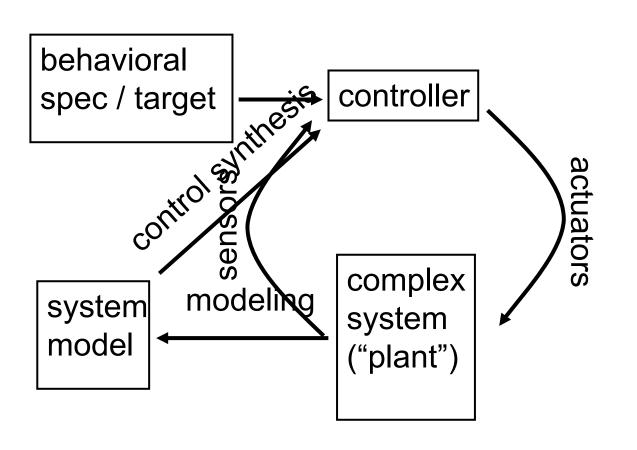


Gadara: Deadlock avoidance in multi-threaded software [OSDI 08, POPL 09, IEEE Computer 09]

Outline

- Motivation
- Control Engineering
- Gadara Walkthrough
- Discussion

Using the Control Engineering Toolkit



"closed-loop"
system provably
satisfies spec:
correct by
construction

Control Engineering

- 100+ years of remarkable success
- Cornerstone for industrial civilization
- Pervasive in everyday life
 - power grid
 - automobile, airplane, spaceship
- Applications in computer systems for quantitative measurements, e.g., performance [Hellerstein, Tilbury, et al. 2004]
- Can this paradigm work for the synthesis of failure-free software?

Discrete Control Theory

- Analogue of conventional control
 - discrete vs. continuous state spaces (not discrete time)
 - event-driven vs. time-driven dynamics
- Modeling formalisms
 - finite automata [workflow control]
 - Petri nets [deadlock avoidance]
- Control synthesis
 - 25 years of research
 - well understood & automated for many models & specs

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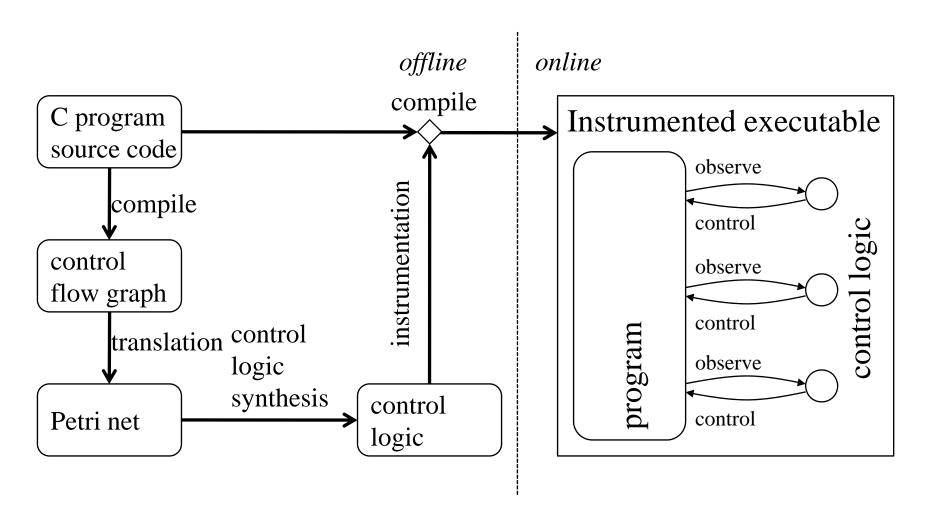
Gadara: Approach

- Model building (Petri net)
- Control logic synthesis
- Source instrumentation



```
void * philosopher(void *arg) {
void * philosopher(void *arg) {
                                                                                                                         if (RAND_MAX/2 > random()) {
  if (RAND MAX/2 > random()) {
                                                                                                                           /* grab A first */
    /* grab A first */
                                                                                                                           gadara lock(&forkA, &ctrlplace);
    pthread mutex lock(&forkA);
                                                                                                                           pthread mutex lock(&forkB);
                                                                 lock(A)
                                                                          lock(B)
    pthread mutex lock(&forkB);
                                                                                                                         clse
  else [
                                                                                                                           /* grab B first */
    /* grab B first */
                                                                                                                           gadara lock(&forkB, &ctrlplace);
    pthread mutex lock(&forkB);
                                                                  lock(B)
                                                                             lock(A)
                                                                                                                           pthread mutex lock(&forkA);
    pthread mutex lock(&forkA);
                                                           unlock(B)
                                                                                                                         gadara replenish(&ctrlplace);
  pthread mutex unlock(&forkA);
                                                                                                                         pthread mutex unlock(&forkA);
  pthread mutex unlock(&forkB);
                                                                                                                         pthread mutex unlock(&forkB);
                                                           unlock(A
```

Architecture



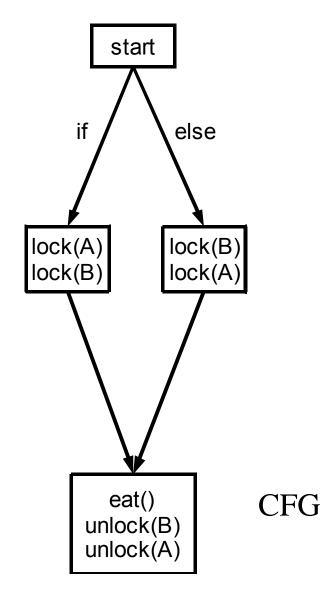
Dining Philosophers

```
void * philosopher(void *arg) {
  if (RAND_MAX/2 > random()) {
    /* grab A first */
    pthread_mutex_lock(&forkA);
    pthread_mutex_lock(&forkB);
  } else {
    /* grab B first */
    pthread_mutex_lock(&forkB);
    pthread_mutex_lock(&forkA);
  eat();
  pthread_mutex_unlock(&forkB);
  pthread_mutex_unlock(&forkA);
```

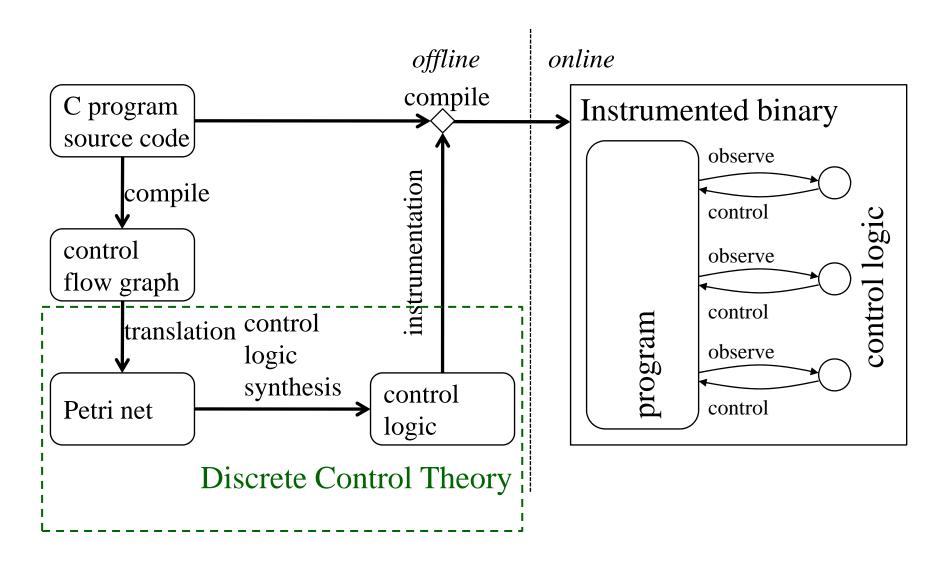
```
int main(int argc, char *argv[]) {
  pthread_create(&p1, NULL,
    philosopher, NULL);
  pthread_create(&p2, NULL,
    philosopher, NULL);
```

Dining Philosophers

```
void * philosopher(void *arg) {
  if (RAND_MAX/2 > random()) {
    /* grab A first */
    pthread_mutex_lock(&forkA);
    pthread_mutex_lock(&forkB);
  } else {
    /* grab B first */
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  pthread mutex unlock(&forkA);
```

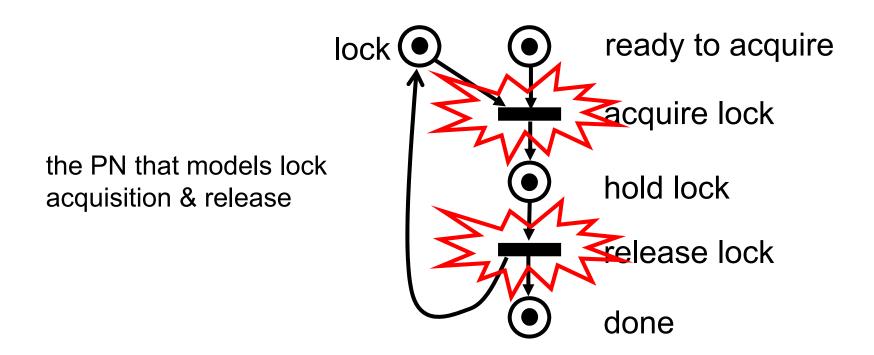


Architecture



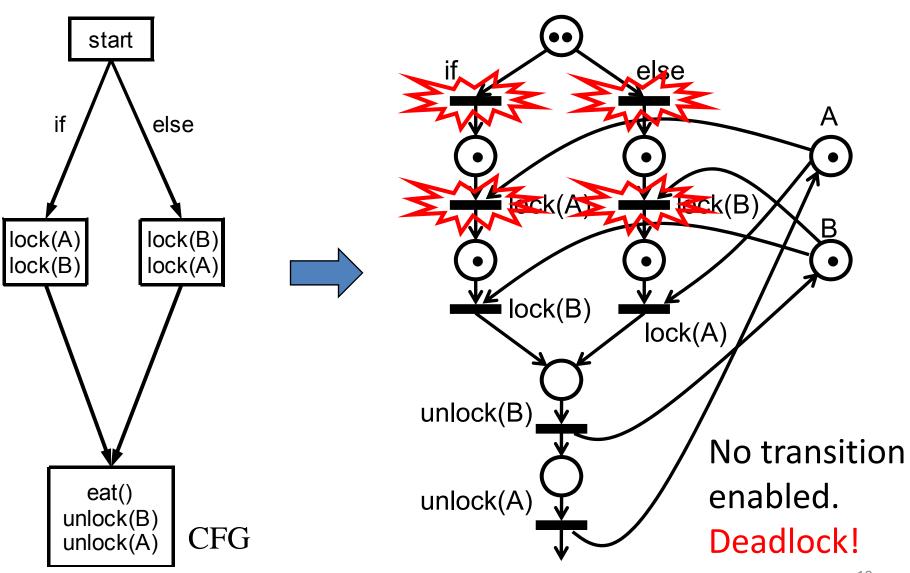
Petri Net Basics

- bipartite graph: two kinds of nodes
- tokens represent states and dynamics

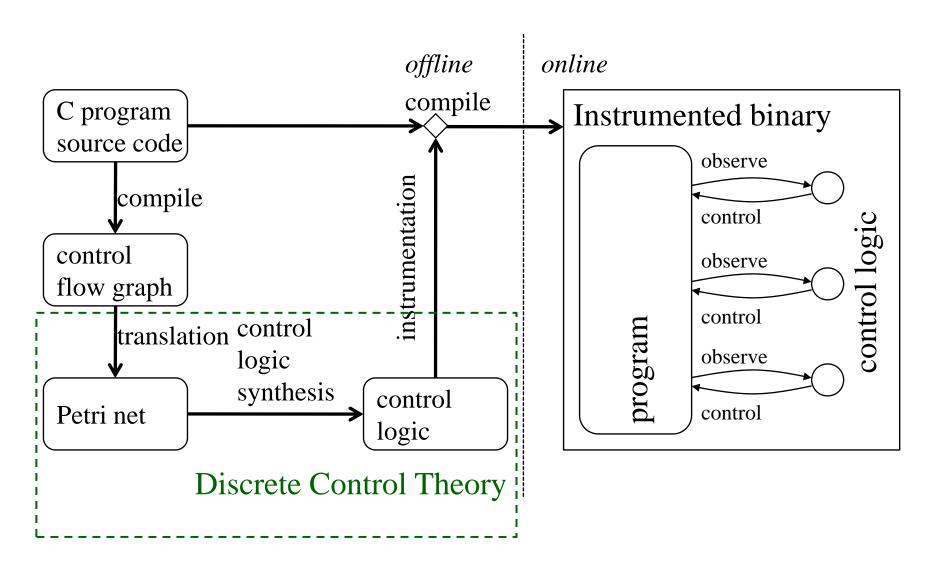


Murata, *Proc. IEEE* 1989 Kavi et al., *IJoPP* 2002

Dining Philosophers

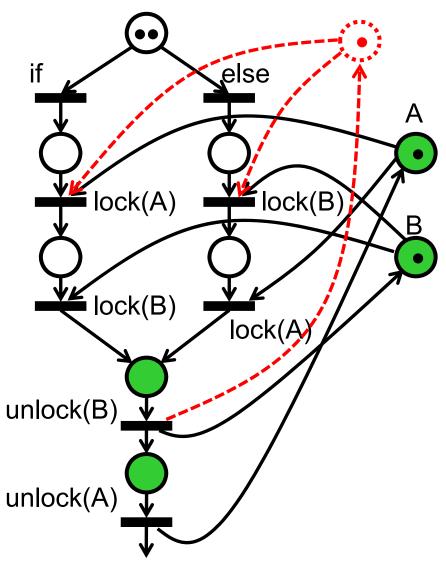


Architecture

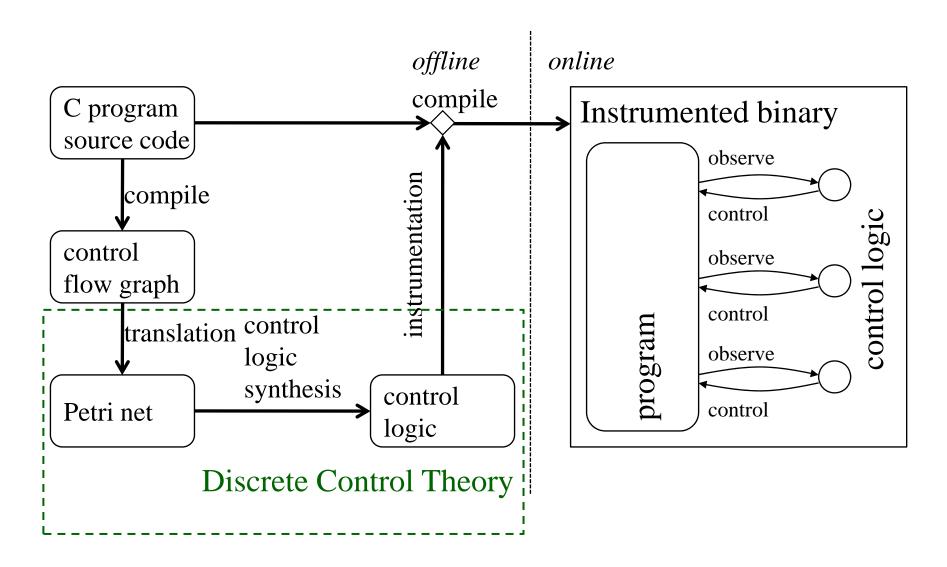


Siphon Based Control

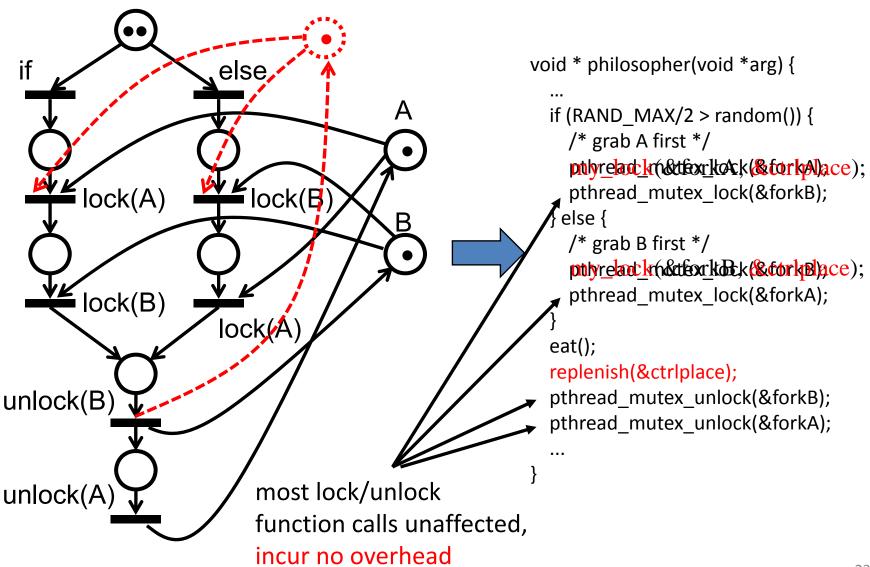
- Siphon is a set of places that can lose tokens permanently
 - structural property
 - related to deadlock
- Synthesize control place to prevent empty siphon
 - linear algebra
 - maximally permissive
- Control logic is
 - fine-grained
 - highly concurrent
 - easy to implement



Architecture



Dining Philosophers: instrumentation



Challenges for Large Scale Software

- Modeling
 - language features
 - Handles: function pointer, recursion
 - Ignores: setjmp, longjmp, exception/signal
 - data flow ambiguity: local annotations
 - dynamically selected locks: type analysis
- Control logic synthesis
 - uncontrollability: report at compile time
 - scalability: decomposition & pruning
 - completeness: other synchronization primitives

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Performance Evaluation

- Pub-Sub benchmark [OSDI 08]
 - injected deadlocks in common-case logic
 - outperforms Intel STM compiler
 - negligible response time overhead under moderate load
 - 18% throughput reduction with overload workload
- OpenLDAP v2.2.20 [OSDI 08]
 - known & unknown deadlocks in corner-case logic
 - negligible overhead with default configuration
 - at most 11% overhead with bizarre pessimistic configuration
- BIND v9.3.0a0 [Wang, Ph.D Thesis 2009]
 - real workload (trace replay of HP named log)
 - 15% overhead with overload query workload

25 18 August 2010

Discrete Control: Benefits

- Provably correct controlled behavior
- Maximal permissiveness
 - Maximal concurrency
- Minimal instrumentation [wodes 2010]
- Offline synthesis + online control
 - Optimal control logic synthesized offline
 - Light-weight control at runtime

Discrete Control: Extensions

- Control specification
 - Linear specification: $l^TM > b$
 - Forbidden state
- Uncontrollable transitions
 - Branches, loops
- Unobservable transitions
 - Library interposition, System calls
- Distributed systems

Conclusions

- Discrete Control Theory provides a principled foundation for the synthesis of provablycorrect software
- Gadara eliminates deadlocks from real programs with acceptable overhead
- Useful in several situations
 - rapid prototype development
 - post-release bug fixing

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Lessons Learned

- Modeling
 - The difficulty can never be overestimated
 - Identify the right level of abstraction
- Control synthesis
 - Leverage existing literature and inspire the community
 - Fully exploit the features of the class of models
- Implementation
 - Experimental science
 - Practicality is the top priority

Other Applications Under Investigation

- Lock synthesis for atomic sections
 - Yu Liu (SUNY), Scott Smith (JHU)
- Distributed diagnosis in sensor networks
 - Matt Welsh (Harvard)
- Enforcing correct interleaving in concurrent software
 - Satish Narayanasamy (U. of Michigan)
- Controlled simulation of embedded systems
 - Stefan Resmerita (Toyota)

Discussion

- Will new parallel languages or language features make Gadara and other tools unnecessary?
- To what extent can tools, e.g., testing, static analysis, runtime analysis, and control synthesis, help eliminate software bugs?
- Is software synthesis practical, how much can we synthesize automatically?
- Can we automate model building according to the class of control specifications?

Thank You