

# Stochastic Zero-sum and Nonzero-sum $\omega$ -regular Games

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A Survey of Results  
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Chess Review  
May 11, 2005



## Outline

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1. Stochastic games: informal descriptions.
2. Classes of game graphs.
3. Objectives.
4. Strategies.
5. Outline of results.
6. Open Problems.



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## Stochastic Games

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- Games played on game graphs with stochastic transitions.
- Stochastic games [Sha53]
  - Framework to model natural interaction between components and agents.
    - e.g., controller vs. system.

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## Stochastic Games

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- **Where:**
  - Arena: Game graphs.
- **What for:**
  - Objectives -  $\omega$ -regular.
- **How:**
  - Strategies.

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## Game Graphs

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- Two broad class:
  - Turn-based games
    - Players make moves in turns.
  - Concurrent games
    - Players make moves simultaneously and independently.

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## Classification of Games

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- Games can be classified in two broad categories:
  - Zero-sum games:
    - Strictly competitive, e.g., Matrix games.
  - Nonzero-sum games:
    - Not strictly competitive, e.g., Bimatrix games.

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## Goals

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- Determinacy: **minmax** and **maxmin** values for zero-sum games.
- Equilibrium: existence of **equilibrium** payoff for nonzero-sum games.
- Computation issues.
- Strategy classification: simplest class of strategies that suffice for determinacy and equilibrium.

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# Turn-based Games

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## Turn-based Probabilistic Games

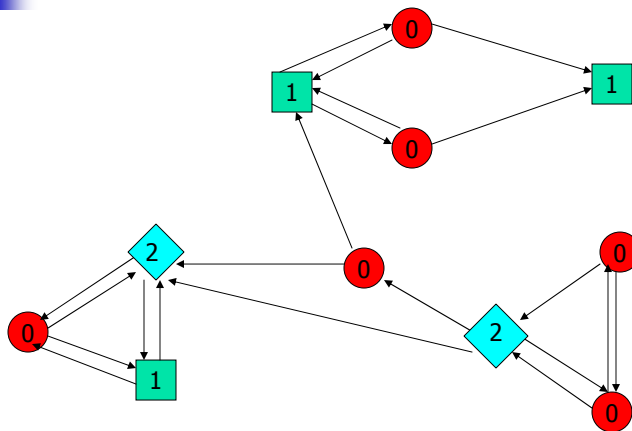
- A turn-based probabilistic game is defined as
  - $G=(V,E,(V_1,V_2,V_0))$ , where
    - $(V,E)$  is a graph.
    - $(V_1,V_2,V_0)$  is a partition of  $V$ .
  - $V_1$  player 1 makes moves.
  - $V_2$  player 2 makes moves.
  - $V_0$  randomly chooses successors.

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## A Turn-based Probabilistic Game



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## Special Cases

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- Turn-based deterministic games:
  - $V_0 = \phi$  (emptyset).
  - No randomness, deterministic transition.
- Markov decision processes (MDPs)
  - $V_2 = \phi$  (emptyset).
  - No adversary.

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## Applications

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- MDPs (1 1/2- player games)
  - Control in presence of uncertainty.
  - Games against nature.
- Turn-based deterministic games (2-player games)
  - Control in presence of adversary, control in open environment or controller synthesis.
  - Games against adversary.
- Turn-based stochastic games (2 1/2 -player games)
  - Control in presence of adversary and nature, controller synthesis of stochastic reactive systems.
  - Games against adversary and nature.

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## Game played

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- Token placed on an initial vertex.
- If current vertex is
  - Player 1 vertex then player 1 chooses successor.
  - Player 2 vertex then player 2 chooses successor.
  - Player random vertex proceed to successors uniformly at random.
- Generates infinite sequence of vertices.

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## Concurrent Games

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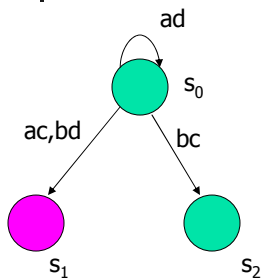
## Concurrent game

- Players make move simultaneously.
- Finite set of **states**  $S$ .
- Finite set of **actions**  $\Sigma$ .
- Action assignments
  - $\Gamma_1, \Gamma_2: S \rightarrow 2^\Sigma \setminus \emptyset$
- **Probabilistic transition function**
  - $\delta(s, a_1, a_2)(t) = \Pr [ t \mid s, a_1, a_2 ]$

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## Concurrent game



Actions at  $s_0$ : a, b for player 1,  
c, d for player 2.

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## Concurrent games

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- Games with simultaneous interaction.
- Model synchronous interaction.

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## Stochastic games

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1 ½ pl.
2 pl.
2 ½ pl.
Conc. games

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# Objectives

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## Plays

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- Plays: infinite sequence of vertices or infinite trajectories.
- $V^\omega$ : set of all infinite plays or infinite trajectories.

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## Objectives

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- **Plays**: infinite sequence of vertices.
- **Objectives**: subset of plays,  $\Psi_1 \subseteq V^\omega$ .
- Play is winning for player 1 if it is in  $\Psi_1$ .
- Zero-sum game:  $\Psi_2 = V^\omega \setminus \Psi_1$ .

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## Reachability and Safety

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- Let  $R \subseteq V$  set of target vertices. Reachability objective requires to visit the set  $R$  of vertices.
- Let  $S \subseteq V$  set of safe vertices. Safety objective requires never to visit any vertex outside  $S$ .

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## Buchi Objective

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- Let  $B \subseteq V$  a set of Buchi vertices. Buchi objective requires that the set  $B$  is visited infinitely often.

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## Rabin-Streett

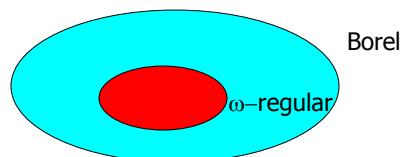
- Let  $\{(E_1, F_1), (E_2, F_2), \dots, (E_d, F_d)\}$  set of vertex set pairs.
  - Rabin: requires there is a pair  $(E_j, F_j)$  such that  $E_j$  finitely often and  $F_j$  infinitely often.
  - Streett: requires for every pair  $(E_j, F_j)$  if  $F_j$  infinitely often then  $E_j$  infinitely often.
  - Rabin-chain: both a Rabin-Streett, complementation closed subset of Rabin.

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## Objectives

- $\omega$ -regular:  $\cup, \circ, *, \omega$ .
  - Safety, Reachability, Liveness, etc.
  - Rabin and Streett canonical ways to express.



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# Strategies

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## Strategy

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- Given a finite sequence of vertices, (that represents the history of play) a strategy  $\sigma$  for player 1 is a probability distribution over the set of successor.

- $\sigma : V^* \cdot V_1 \rightarrow D$

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## Subclass of Strategies

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- Memoryless (stationary) strategies: Strategy is independent of the history of the play and depends on the current vertex.
  - $\sigma : V_1 \rightarrow D$
- Pure strategies: chooses a successor rather than a probability distribution.
- Pure-memoryless: both pure and memoryless (simplest class).

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## Strategies

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- The set of strategies:
  - Set of strategy  $\Sigma$  for player 1; strategies  $\sigma$ .
  - Set of strategy  $\Pi$  for player 2; strategies  $\pi$ .

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## Values

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- Given objectives  $\Psi_1$  and  $\Psi_2 = V^\omega \setminus \Psi_1$  the value for the players are
  - $v_1(\Psi_1)(v) = \sup_{\sigma \in \Sigma} \inf_{\pi \in \Pi} \Pr_v^{\sigma, \pi}(\Psi_1)$ .
  - $v_2(\Psi_2)(v) = \sup_{\pi \in \Pi} \inf_{\sigma \in \Sigma} \Pr_v^{\sigma, \pi}(\Psi_2)$ .

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## Determinacy

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- **Determinacy:**  $v_1(\Psi_1)(v) + v_2(\Psi_2)(v) = 1$ .
- Determinacy means
  - $\sup \inf = \inf \sup$ .
  - von Neumann's minmax theorem in matrix games.

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## Optimal strategies

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- A strategy  $\sigma$  is optimal for objective  $\Psi_1$  if
  - $v_1(\Psi_1)(v) = \inf_{\pi} \Pr_v^{\sigma, \pi}(\Psi_1)$ .
- Analogous definition for player 2.

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## Zero-sum and nonzero-sum games

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- Zero sum:  $\Psi_2 = V^\omega \setminus \Psi_1$ .
- Nonzero-sum:  $\Psi_1$  and  $\Psi_2$ 
  - happy with own goals.

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## Concept of rationality

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- Zero sum game: Determinacy.
- Nonzero sum game: Nash equilibrium.

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## Nash Equilibrium

- A pair of strategies  $(\pi_1, \pi_2)$  is an  $\varepsilon$ -Nash equilibrium if
  - For all  $\pi'_1, \pi'_2$ :
    - $\text{Value}_2(\pi_1, \pi'_2) \leq \text{Value}_2(\pi_1, \pi_2) + \varepsilon$
    - $\text{Value}_1(\pi'_1, \pi_2) \leq \text{Value}_1(\pi_1, \pi_2) + \varepsilon$
  - Neither player has advantage of more than  $\varepsilon$  in deviating from the equilibrium strategy.
  - A 0-Nash equilibrium is called a Nash equilibrium.
  - [Nash's Theorem](#) guarantees existence of Nash equilibrium in nonzero-sum matrix games.

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## Computational Issues

- Algorithms to compute values in games.
- Identify the simplest class of strategies that suffices for optimality or equilibrium.

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# Outline of results

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## History and results

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- MDPs
  - Complexity of MDPs. [PapTsi89]
  - MDPs with  $\omega$ -regular objectives. [CouYan95,deAl97]

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## History and results

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- Two-player games.
  - Determinacy ( $\sup \inf = \inf \sup$ ) theorem for Borel objectives. [Mar75]
  - Finite memory determinacy (i.e., finite memory optimal strategy exists) for  $\omega$ -regular objectives. [GurHar82]
  - Pure memoryless optimal strategy exists for Rabin objectives. [EmeJut88]
    - NP-complete.

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## History and result

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- 2 1/2 - player games
  - Reachability objectives: [Con92]
    - Pure memoryless optimal strategy exists.
    - Decided in  $NP \cap coNP$ .

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## History and results: Concurrent zero-sum games

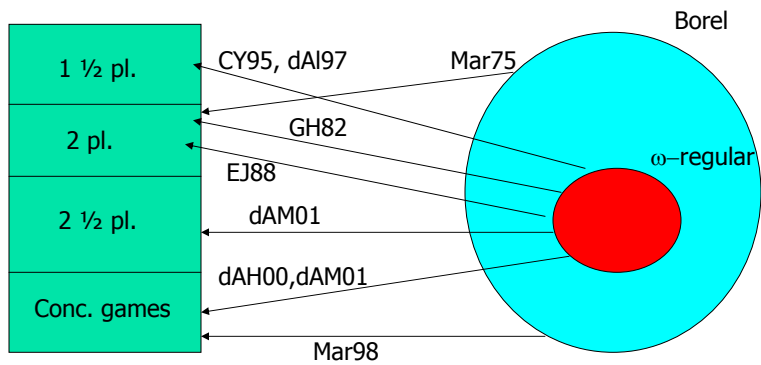
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- Detailed analysis of concurrent games [FilVri97].
- Determinacy theorem for all Borel objectives [Mar98].
- Concurrent  $\omega$ -regular games:
  - Reachability objectives [deAlHenKup98].
  - Rabin-chain objectives [deAlHen00].
  - Rabin-chain objectives [deAlMaj01].

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## Zero sum games



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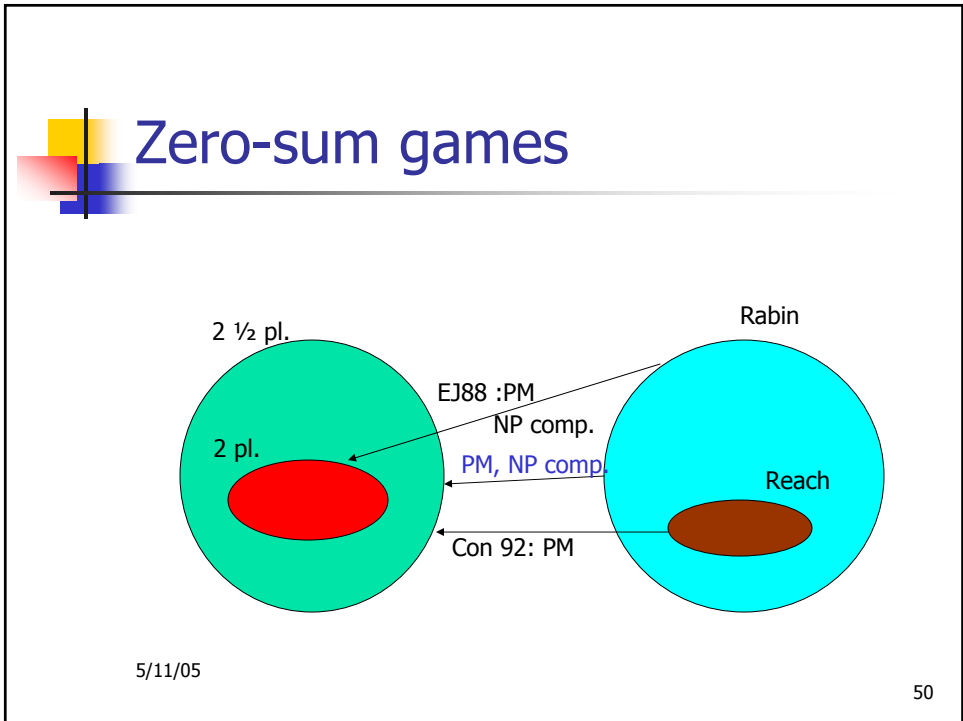
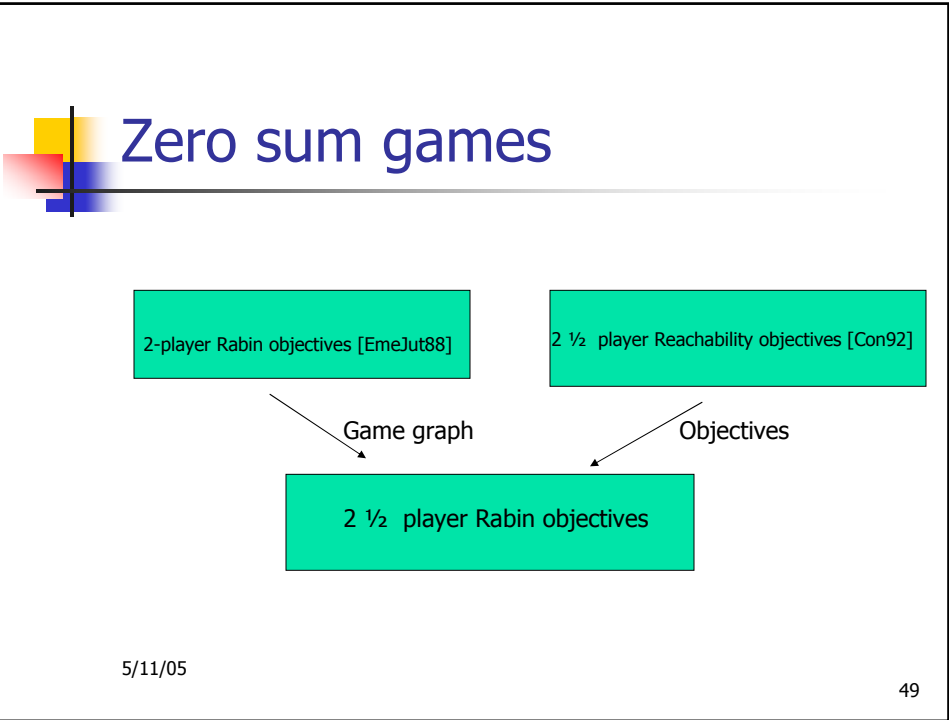
## Zero sum games

- 2 1/2 player games with Rabin and Streett objectives [CdeAlHen 05a]
  - Pure memoryless optimal strategies exist for Rabin objectives in 2 1/2 player games.
  - 2 1/2 player games with Rabin objectives is NP-complete.
  - 2 1/2 player games with Streett objectives is coNP-complete.

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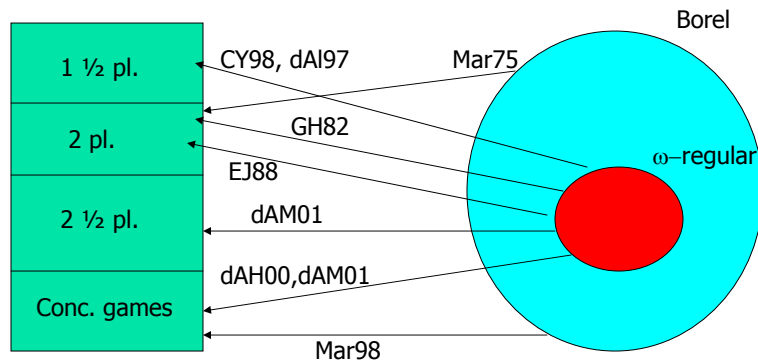
# Zero sum games

- Concurrent games with parity objectives
  - Requires infinite memory strategies even for Buchi objectives [deAlHen00].
  - Polynomial witnesses for infinite memory strategies and polynomial time verification procedure.
  - Complexity:  $NP \cap coNP$  [CdeAlHen 05b].

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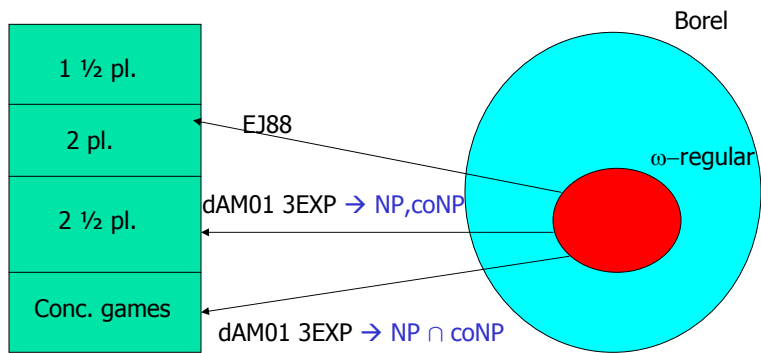
# Zero sum games



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# Zero sum games



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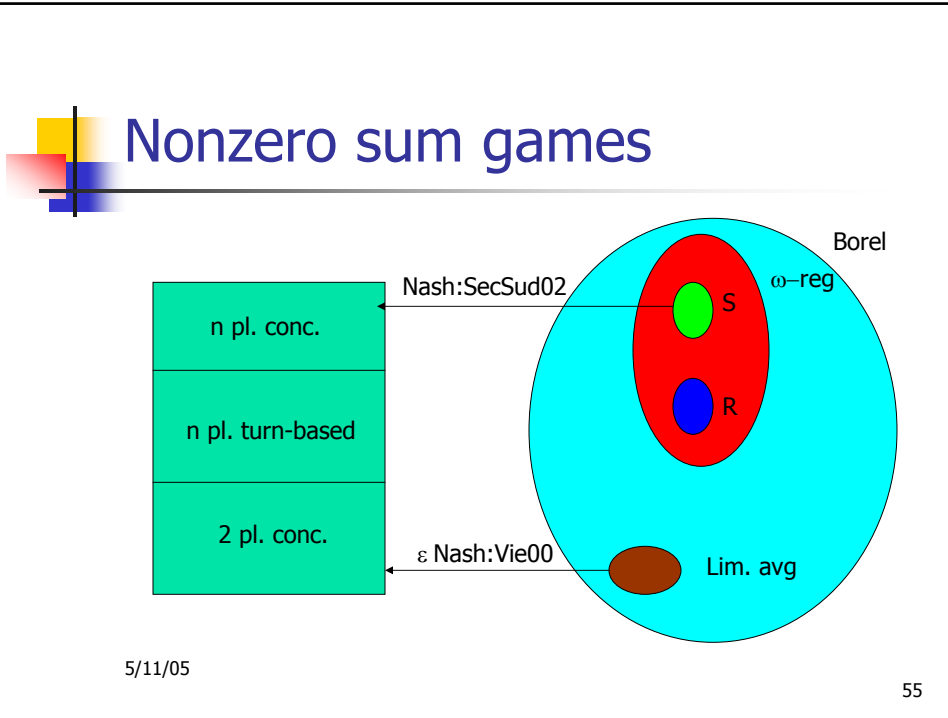
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# History: Nonzero-sum Games

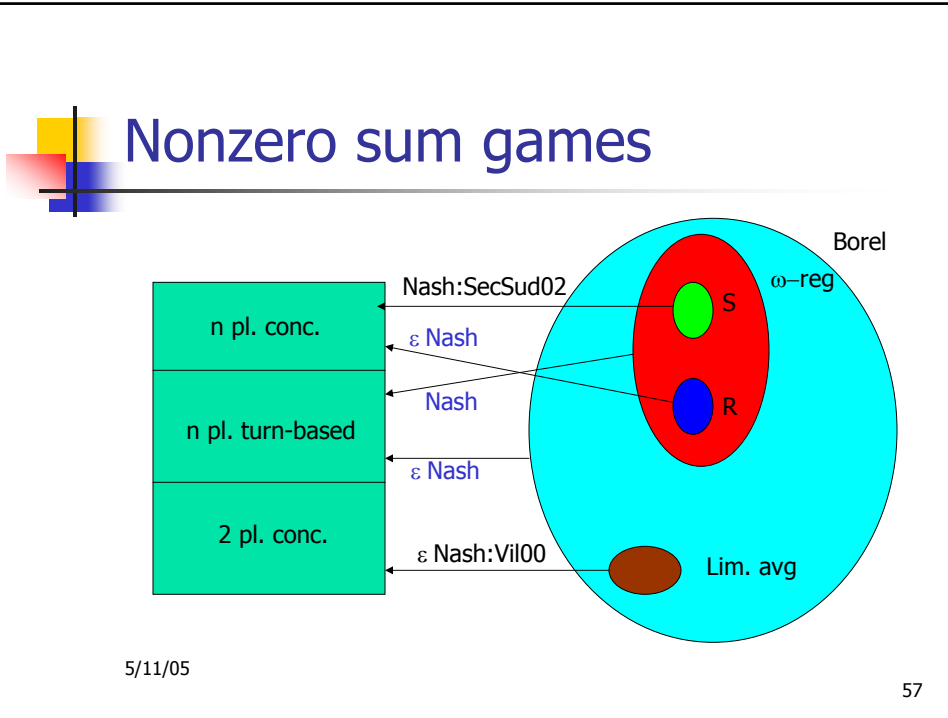
- Two-player nonzero-sum stochastic games with limit-average payoff. [Vie00a, Vie00b]
- Closed sets (Safety). [SecSud02]

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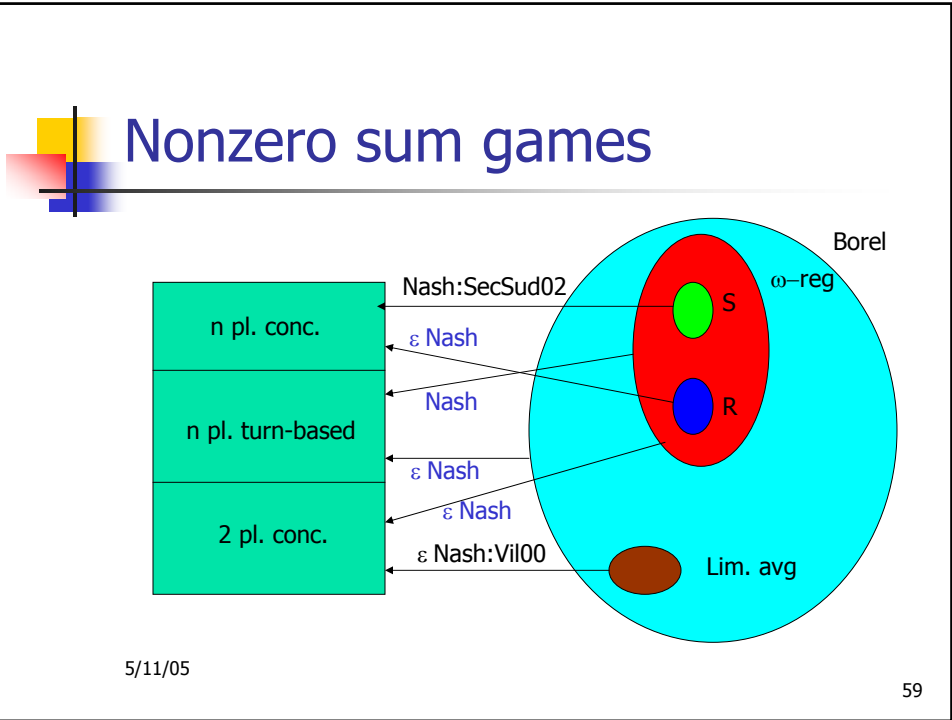
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- # Nonzero sum games
- For all  $n$  player concurrent games with reachability objectives for all players,  $\epsilon$ -Nash equilibrium exist for all  $\epsilon > 0$ , in memoryless strategies [CMajJur 04].
  - For all  $n$  player turn-based stochastic games with Borel objectives for the players,  $\epsilon$ -Nash equilibrium exist for all  $\epsilon > 0$ , in pure strategies [CMajJur 04].
    - The result strengthens to exact Nash equilibria in case of  $n$  player turn based deterministic games with Borel objectives, and  $n$  player turn based stochastic games with  $\omega$ -regular objectives.
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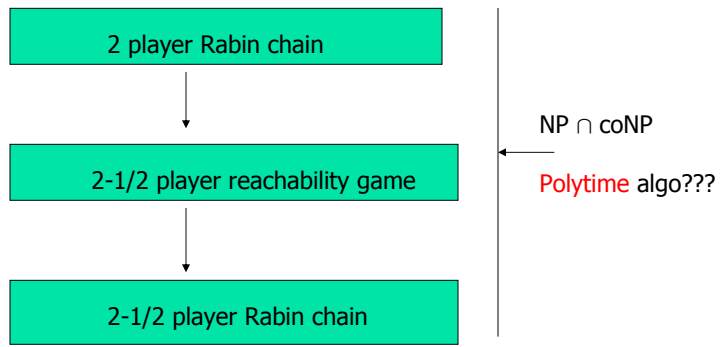


- # Nonzero sum games
- For 2-player concurrent games with  $\omega$ -regular objectives for both players,  $\epsilon$ -Nash equilibrium exist for all  $\epsilon > 0$  [C 05].
  - Polynomial witness and polynomial time verification procedure to compute an  $\epsilon$ -Nash equilibrium.
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  6. **Open Problems.**
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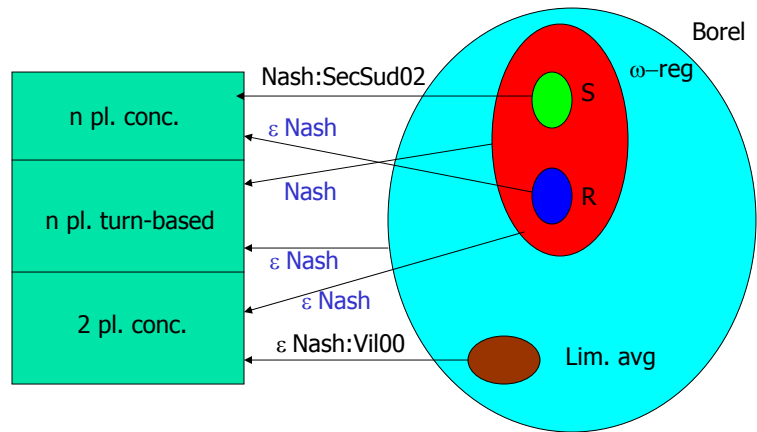
# Major open problems



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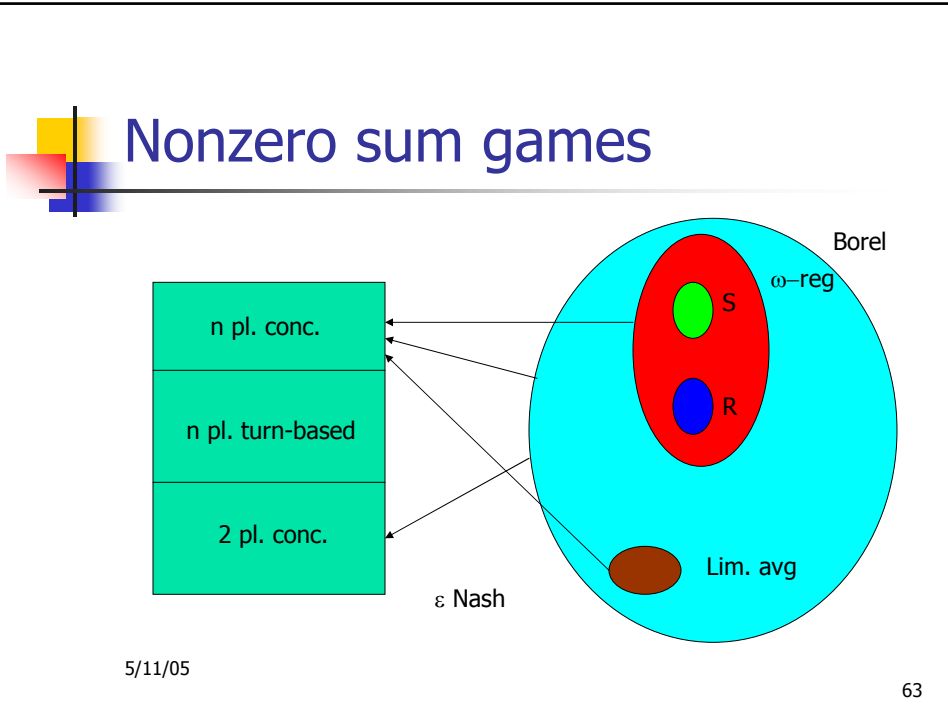
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# Nonzero sum games



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- # Conclusion
- Stochastic games
    - Rich theory.
    - Communities: Descriptive Set Theory, Stochastic Game Theory, Probability Theory, Control Theory, Optimization Theory, Complexity Theory, Formal Verification ... .
    - Several open theoretical problems.
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## Joint work with

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Thomas A. Henzinger  
Luca de Alfaro  
Rupak Majumdar  
Marcin Jurdzinski



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Thanks !!!

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