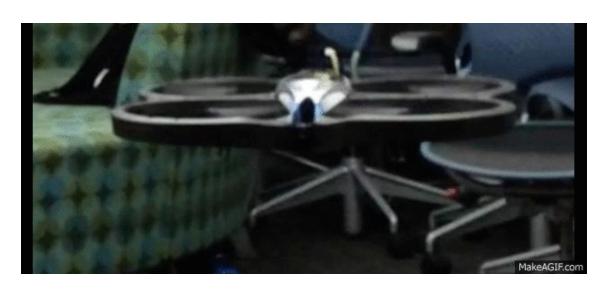
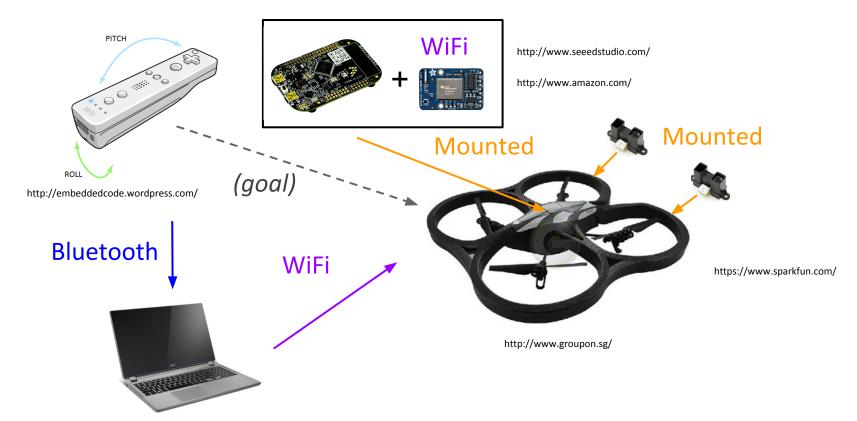
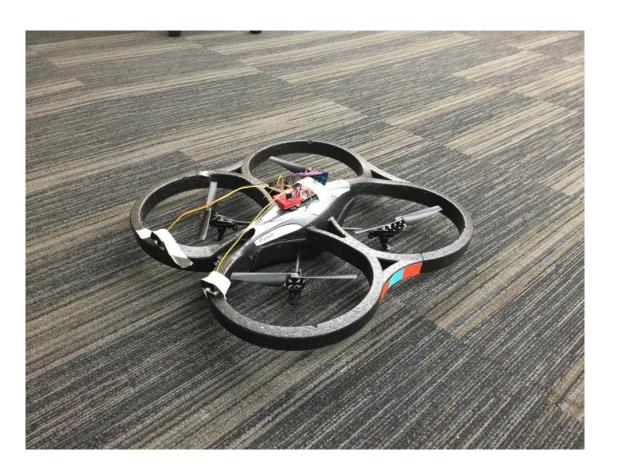
WiiCopter Final Presentation



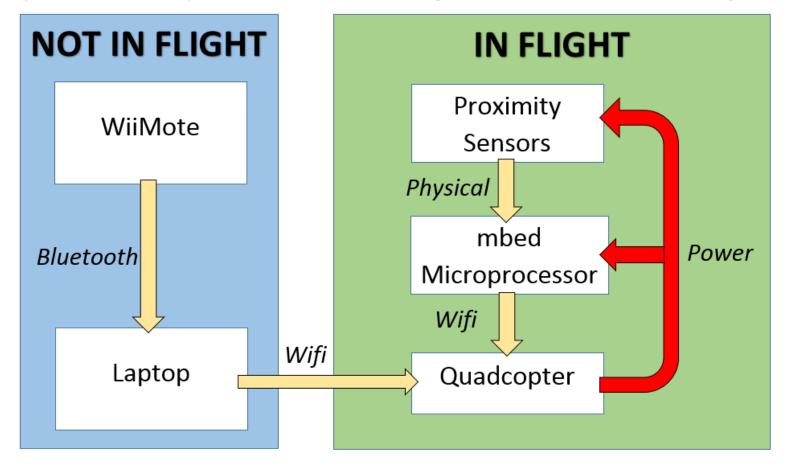
Steve Campos, Gangbaolede Li, Jimmy Su GSI: Antonio Iannopollo

Project Description: Controlling quadcopter w/ Wiimote and incorporating sensors for safety

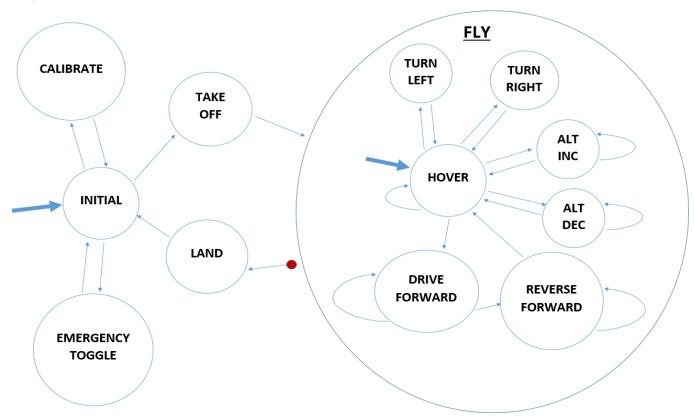




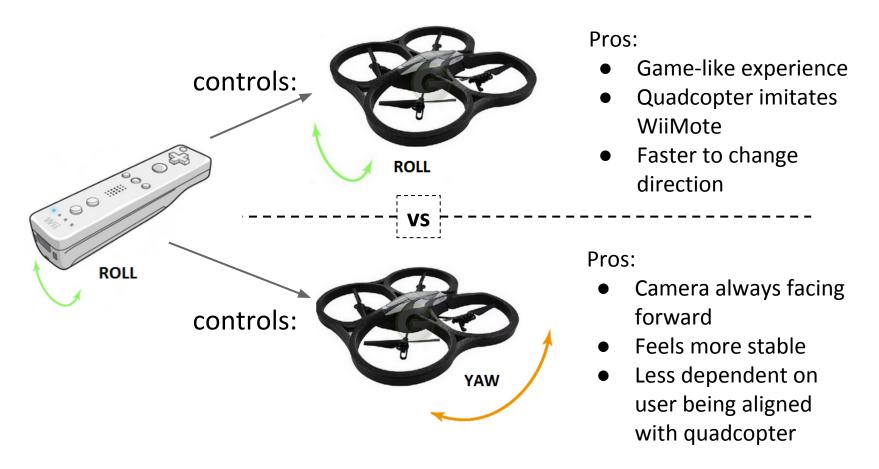
Project Description (Block Diagram of Networking)



Project Functionality - Composition State Machine w/ Preemptive & Reset Transition



Project Implementations - How to Turn



Weight Analysis: Payload max (theoretical) = 200g (experimental) = 120g



Drone (skeleton + cover): 338 [g]



http://www.amazon.com/

AR Drone Battery:

101 [g]



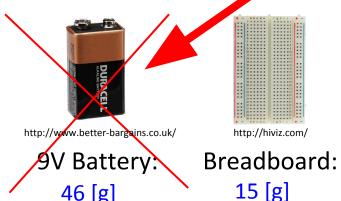
mbed:

21 [g]



wifi module:

5 [g]





Regulator Circuit:

5 [g]



Sensors:

8.5 [g] each



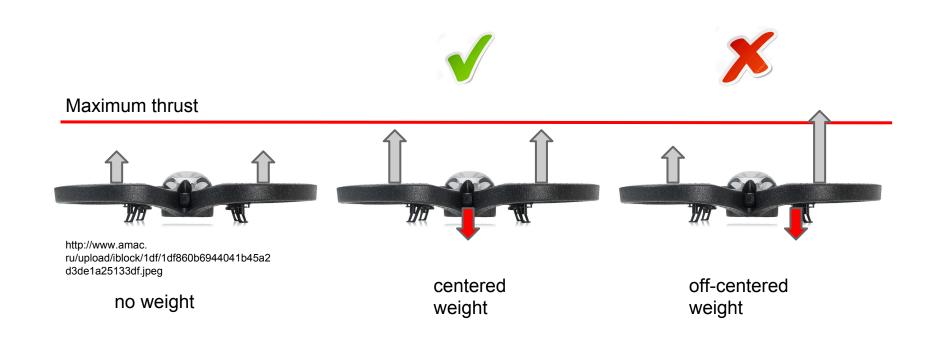
nuts and bolts:

12 [g]

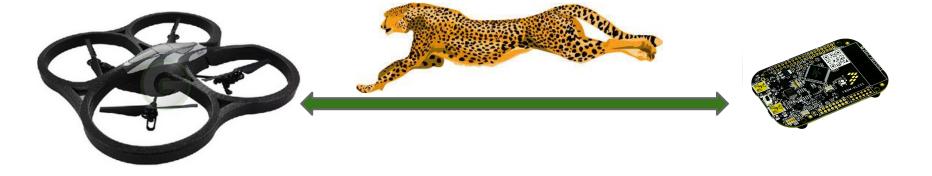
TOTAL PAYLOAD = 138 [g]

= 92 [g]

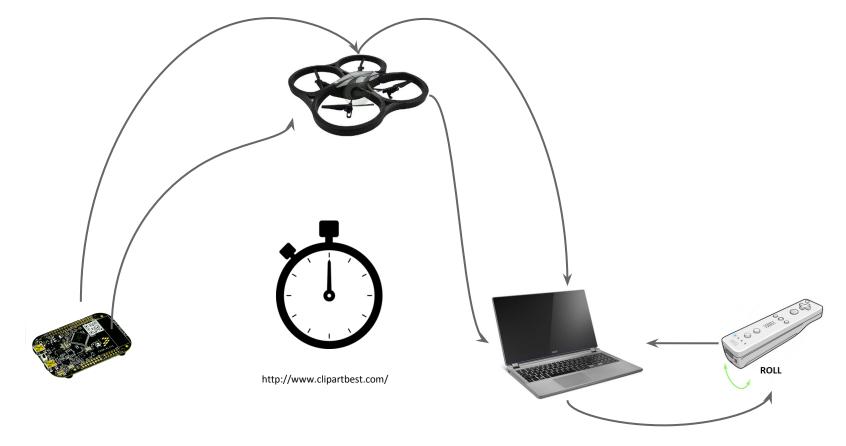
Weight analysis 2 (distribution)



Keeping it real...time

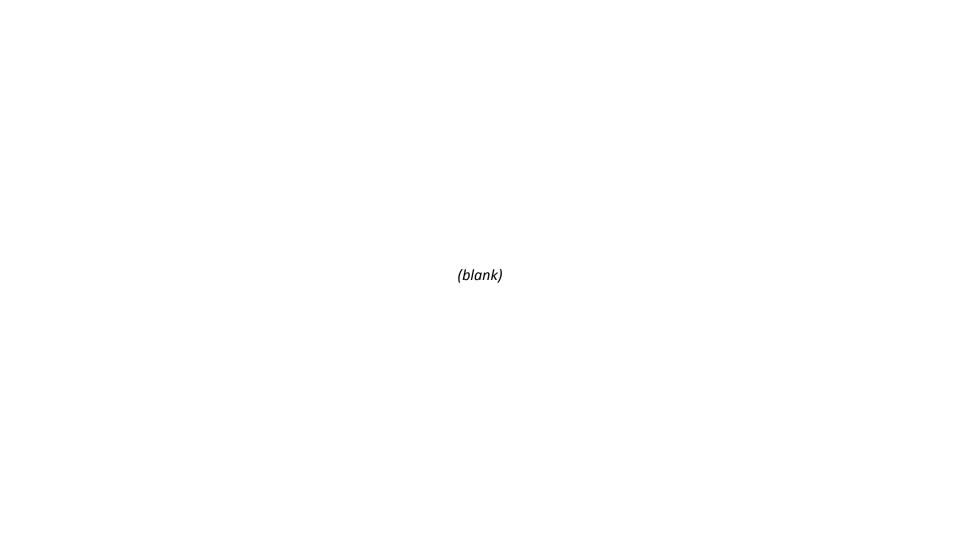


Where rubber meets the road



Conclusion

- ENORMOUS thanks to Antonio lannopollo (our main GSI) for being with us every step of the way, as well as Ben Zhang and John Finn for answering any other questions we had.
- We are grateful to professors Edward Lee and Alberto L.
 Sangiovanni-Vincentelli for giving us deeper insights into the world of embedded systems, as well as solidifying our understanding of the relationship between modelling, design, and analysis.
- Questions?



Resources

http://embeddedcode.wordpress.com/2010/12/07/wiimote-and-glovepie/

http://www.seeedstudio.com/depot/Freescale-FRDMKL25Z-p-1420.html

http://www.amazon.com/ADAFRUIT-INDUSTRIES-BREAKOUT-CC3000-MODULE/dp/B00GQM9IFY

http://ardrone2.parrot.com

https://www.sparkfun.com/products/8958

http://www.groupon.sg/deals/shopping/Groupon-Delivery/716917936

http://www.amazon.com/Bastens-battery-upgrade-Parrot-AR-Drone/dp/B004WPITUC

http://hiviz.com/kits/instructions/du-manual.htm

http://www.better-bargains.co.uk/duracell-9v-battery.html

http://www.clipartbest.com/cliparts/niB/gXj/niBgXjoiA.png